

Image https://www.wallpaperflare.com/person-touching-body-of-water-person-touching-body-of-water-during-daytime-wallpaper-zthoe



Learning Goals

- The somatosensory system
- Haptics
- Applications in HCI

Somatosensory System

 informs us about objects in our external environment through touch and about the position and movement of our body parts through the stimulation of muscle and joints.

Patrick Dougherty, Department of Anesthesiology and Pain Medicine, MD Anderson Cancer Center (content provided by Chieyeko Tsuchitani), https://nba.uth.tmc.edu/neuroscience/m/s2/chapter02.html



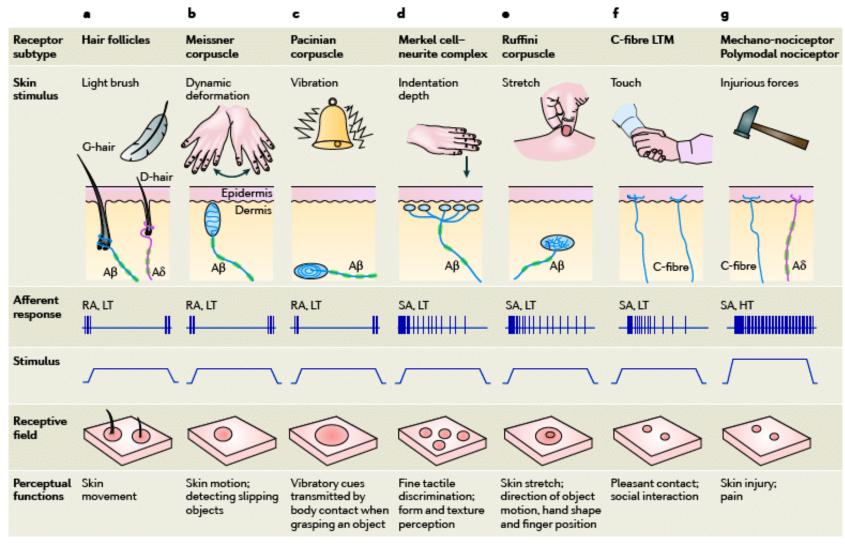
Katrin Wolf



Haptics 5 Katrin Wolf



Katrin Wolf



Mechanoreceptors

RA/SA rapidly/slowly adapting; LT/HT low/high threshold

Suslak, Thomas. (2015). There and back again: a stretch receptor's tale. Thesis, https://www.researchgate.net/publication/292449835_There_and_back_again_a_stretch_receptor's_tale

Haptics

8

Somatosensory System

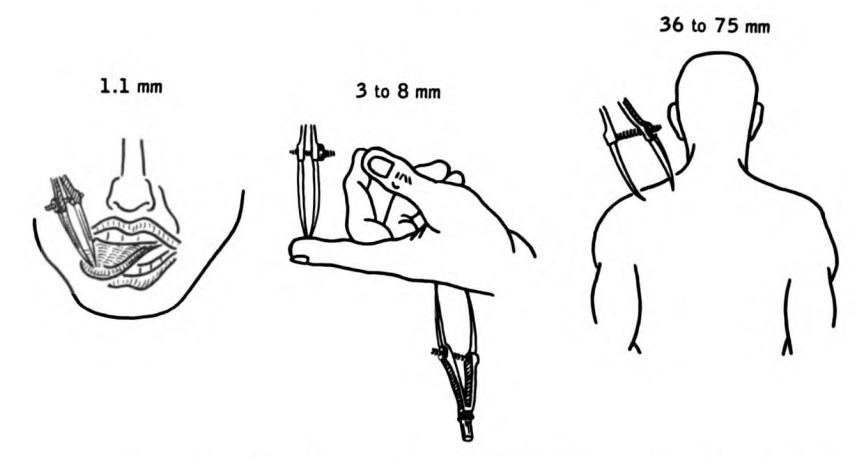


Image Source https://en.wikipedia.org/wiki/Two-point_discrimination#/media/File:Lawrence_1960_8.11.png by House, Earl Lawrence. Pansky, Ben. - A functional approach to neuroanatomy 1960

Slide adapted from Tonja Machulla

Somatosensory System

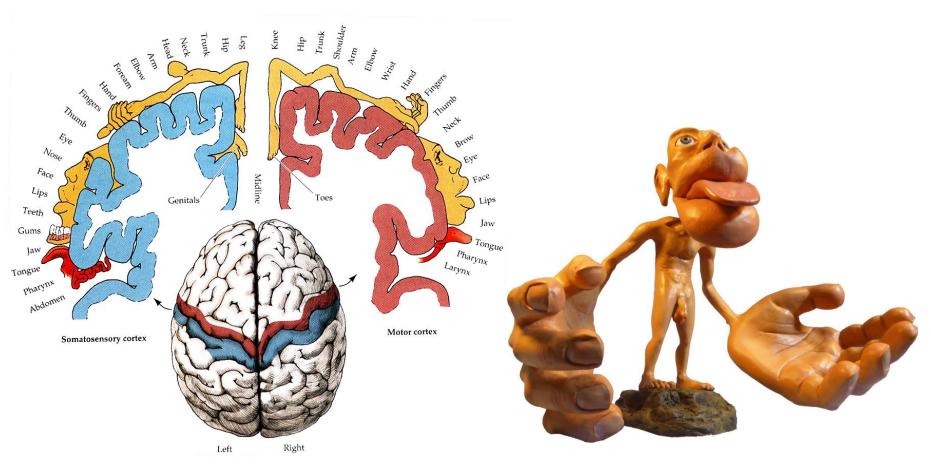


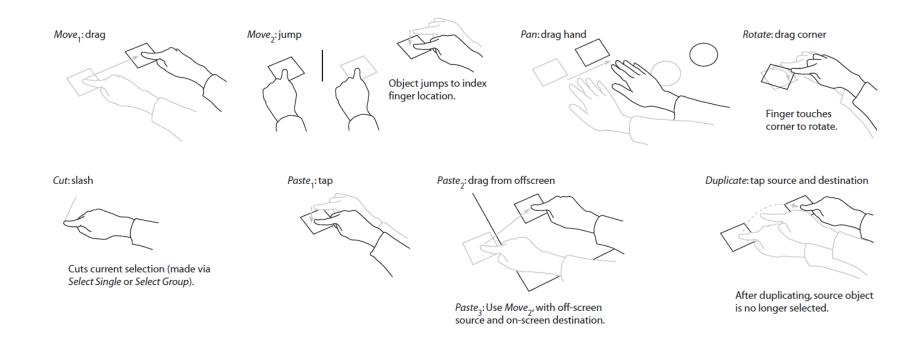
Image adapted from https://www.flickr.com/photos/46006858@N05/8641421501 by Gary Kirwan & https://en.wikipedia.org/wiki/Cortical_homunculus#/media/File:Front_of_Sensory_Homunculus.gif by Mpj29

Haptics 10 Katrin Wolf

- Haptic perception: active exploration of surfaces and objects by a moving subject, as opposed to passive contact by a static subject during tactile perception.¹
- Haptic technology: creates an experience of touch by applying forces, vibrations, or motions to the user.²

1 Weber, E. H. (1851). Die Lehre vom Tastsinne und Gemeingefühle auf Versuche gegründet. Friedrich Vieweg und Sohn | 2 Gabriel Robles-De-La-Torre. "International Society for Haptics: Haptic technology, an animated explanation". Isfh.org. Archived from the original on 2010-03-07

Haptics 11 Katrin Wolf



Jacob O. Wobbrock, Meredith Ringel Morris, and Andrew D. Wilson. 2009. User-defined gestures for surface computing. CHI '09

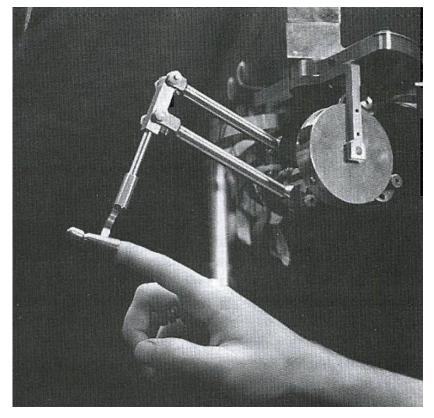


Image Source https://www.needpix.com/photo/1005794/mobile-phone-smartphone-mobile-phone-phone-icon-to-call-screen-phone-call-call by ElisaRiva



Image Source Raphael Wimmer and Sebastian Boring. 2009. HandSense: discriminating different ways of grasping and holding a tangible user interface. TEI '09

Haptics 14 Katrin Wolf

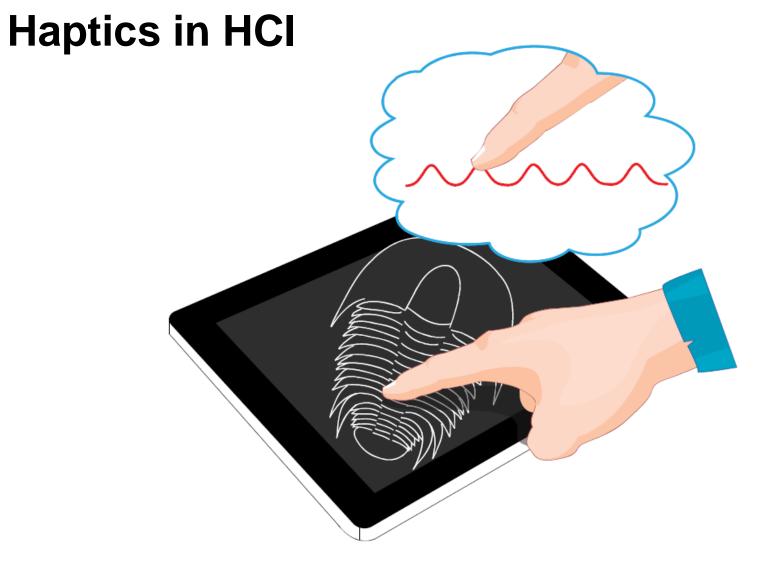


Massie, T. H., & Salisbury, J. K. (1994, November). The phantom haptic interface: A device for probing virtual objects. In *Proceedings of the ASME winter annual meeting, symposium on haptic interfaces for virtual environment and teleoperator systems* (Vol. 55, No. 1, pp. 295-300).

Haptics 15 Katrin Wolf



Haptics 16 Katrin Wolf



Seung-Chan Kim, Ali Israr, and Ivan Poupyrev. 2013. Tactile rendering of 3D features on touch surfaces. UIST '13

Haptics 17 Katrin Wolf



Haptics 18 Katrin Wolf

This file is licensed under the Creative Commons Attribution-Share Alike 4.0 (CC BY-SA) license:

https://creativecommons.org/licenses/by-sa/4.0

Attribution: Katrin Wolf

For more content see: https://hci-lecture.de

